

FEATURES

- 12 parallel channel GPS receiver
- 4000 simultaneous time-frequency search bins
- SBAS (WAAS, EGNOS) support
- -137dBm acquisition sensitivity
- -145dBm tracking sensitivity
- < 10 second hot start</p>
- < 45 second cold start
- 5m CEP accuracy

LS-40EB

Fast Acquisition Enhanced Sensitivity 12 Channel GPS Sensor Module

The LS-40EB module is a small, single-board, 12 parallel-channel receiver intended for Original Equipment Manufacturer (OEM) products.

The receiver continuously tracks all satellites in view and provides accurate satellite positioning data. The LS-40EB is optimized for applications requiring good performance, low cost, and maximum flexibility; suitable for a wide range of OEM configurations including handhelds, asset tracking, marine and vehicle navigation products.

Its 12 parallel channels and 4000 search bins provide fast satellite signal acquisition and short startup time. Acquisition sensitivity of -137dBm and tracking sensitivity of -145dBm offers good navigation performance even in urban canyons having limited sky view.

Satellite-based augmentation systems, such as WAAS and EGNOS, are supported to yield improved accuracy.

TECHNICAL SPECIFICATIONS

Receiver Type 12 parallel channel, L1 C/A code

Accuracy Position 5m CEP

Velocity 0.1m/sec

Startup Time < 10sec hot start

< 35sec warm start < 45sec cold start

Signal Reacquisition 1s

Sensitivity -137dBm acquisition

-145dBm tracking

Update Rate 1Hz

Dynamics 4G (39.2m/sec²)

Operational Limits Altitude < 18,000m or velocity < 515m/s

(COCOM limit, either may be exceeded but not both)

Serial Interface LVTTL level

Protocol NMEA-0183 V3.01

GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG, GPZDA

4800 baud, 8, N, 1

Datum Default WGS-84

User definable

RF Connector MMCX

Interface Connector 10 pin 2.0mm pitch male header

Input Voltage 3.3V DC +/-100mV

Current Consumption 67 ~ 90mA

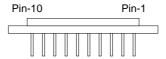
Dimension 43.3mm L x 31.4mm W x 5.8mm H

Weight: 10g

Operating Temperature -40°C ~ +85°C

Humidity 5% ~ 95%

PINOUT DESCRIPTION



LS-40EB Lateral View

Pin Number	Signal Name	Description
1	Serial Data Out 1	Asynchronous serial output at LVTTL level, to output NMEA message
2	Serial Data In 1	Asynchronous serial input at LVTTL level, to input commands
3	VCC	Regulated 3.3V power input
4	GND	Ground
5	PIO Output	PIO output, default used for GPS status indication
6	1PPS	1 pulse per second time mark
7	RESET IN	Reset input, active LOW
8	Serial Data In 2	Asynchronous serial input at LVTTL level, to input DGPS RTCM data
9	VBAT	Optional 3.3V backup power input to sustain RTC and SRAM data
10	Antenna Power	Power input for active antenna

NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - GPS FIX DATA

Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:

\$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:

\$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	2447.2038	Latitude in ddmm.mmmm format
		Leading zeros transmitted
3	Ν	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	12100.4990	Longitude in dddmm.mmmm format
		Leading zeros transmitted
5	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	1	Position fix quality indicator
		0: position fix unavailable
		1: valid position fix, SPS mode
		2: valid position fix, differential GPS mode
7	06	Number of satellites in use, 00 ~ 12
8	01.7	Horizontal dilution of precision, 00.0 ~ 99.9
9	00078.8	Antenna height above/below mean sea level, -9999.9 ~ 17999.9
10	0016.3	Geoidal height, -999.9 ~ 9999.9
11		Age of DGPS data since last valid RTCM transmission in xxx format (seconds)
		NULL when DGPS not used
12		Differential reference station ID, 0000 ~ 1023
		NULL when DGPS not used
13	5C	Checksum

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '\$' and '*'.

GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS

Latitude and longitude of current position, time, and status.

Format

\$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:

\$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

Field	Example	Description
1	2447.2073	Latitude in ddmm.mmmm format
		Leading zeros transmitted
2	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
3	12100.5022	Longitude in dddmm.mmmm format
		Leading zeros transmitted
4	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
5	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
6	Α	Status, 'A' = valid position, 'V' = navigation receiver warning
7	Α	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
8	65	Checksum

GSA - GPS DOP AND ACTIVE SATELLITES

GPS receiver operating mode, satellites used for navigation, and DOP values.

Format

\$GPGSA,<1>,<2>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

\$GPGSA,A,3,26,21,,,09,17,,,,,10.8,02.1,10.6*07<CR><LF>

Field	Example	Description
1	Α	Mode, 'M' = Manual, 'A' = Automatic
2	3	Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix
3	26,21,,,09,17,,,,,	PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	10.8	Position dilution of precision, 00.0 to 99.9
5	02.1	Horizontal dilution of precision, 00.0 to 99.9
6	10.6	Vertical dilution of precision, 00.0 to 99.9
7	07	Checksum

GSV - GPS SATELLITE IN VIEW

Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:

\$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,...,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:

\$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF>\$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

Field	Example	Description
1	2	Total number of GSV messages to be transmitted
2	1	Number of current GSV message
3	08	Total number of satellites in view, 00 ~ 12
4	26	Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	50	Satellite elevation number, 00 ~ 90 degrees
6	016	Satellite azimuth angle, 000 ~ 359 degrees
7	40	C/No, 00 ~ 99 dB
		Null when not tracking
8	7C	Checksum

RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA

Time, date, position, course and speed data.

Format:

\$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:

\$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	А	Status, 'V' = navigation receiver warning, 'A' = valid position
3	2447.2038	Latitude in dddmm.mmmm format
		Leading zeros transmitted
4	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
5	12100.4990	Longitude in dddmm.mmmm format
		Leading zeros transmitted
6	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
7	016.0	Speed over ground, 000.0 ~ 999.9 knots
8	221.0	Course over ground, 000.0 ~ 359.9 degrees
9	250304	UTC date of position fix, ddmmyy format
10	003.3	Magnetic variation, 000.0 ~ 180.0 degrees
11	W	Magnetic variation direction, 'E' = East, 'W' = West
12	Α	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
13	22	Checksum

VTG - COURSE OVER GROUND AND GROUND SPEED

Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:

GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>*<6><CR><LF>

Example:

\$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

Field	Example	Description
1	221.0	True course over ground, 000.0 ~ 359.9 degrees
2	224.3	Magnetic course over ground, 000.0 ~ 359.9 degrees
3	016.0	Speed over ground, 000.0 ~ 999.9 knots
4	0029.6	Speed over ground, 0000.0 ~ 1800.0 kilometers per hour
5	Α	Mode indicator
		'N' = Data invalid
		'A' = Autonomous
		'D' = Differential
		'E' = Estimated
6	1F	Checksum

ZDA TIME AND DATE

Format:

\$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

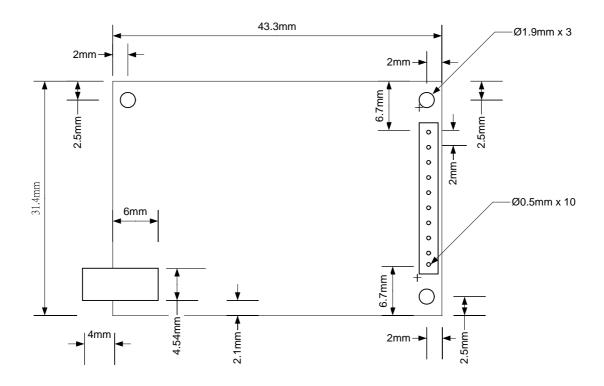
\$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Example	Description
1	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	25	UTC time: day (01 31)
3	03	UTC time: month (01 12)
4	2004	UTC time: year (4 digit year)
5		Local zone hour
		Not being output by the receiver (NULL)
6		Local zone minutes
		Not being output by the receiver (NULL)
7	6C	Checksum

Binary Messages

See Binary Message Protocol User's Guide for detailed descriptions.

MECHANICAL CHARACTERISTICS



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